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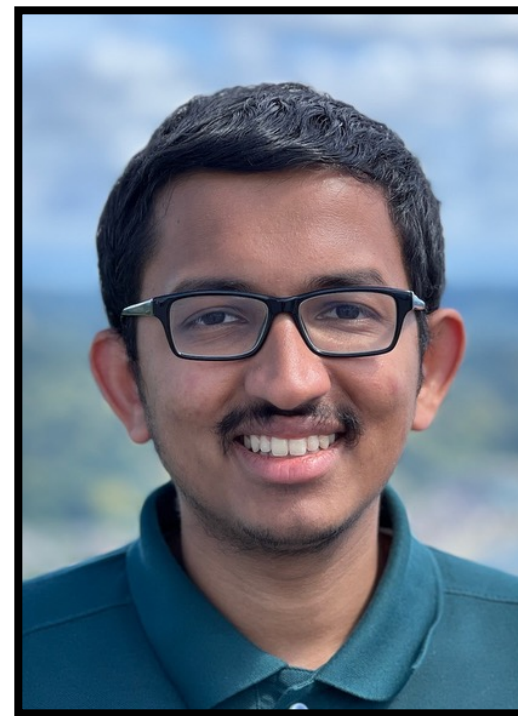
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EUROPEAN CONFERENCE ON COMPUTER VISION

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Discover-then-Name: Task-Agnostic Concept Bottlenecks via Automated Concept Discovery



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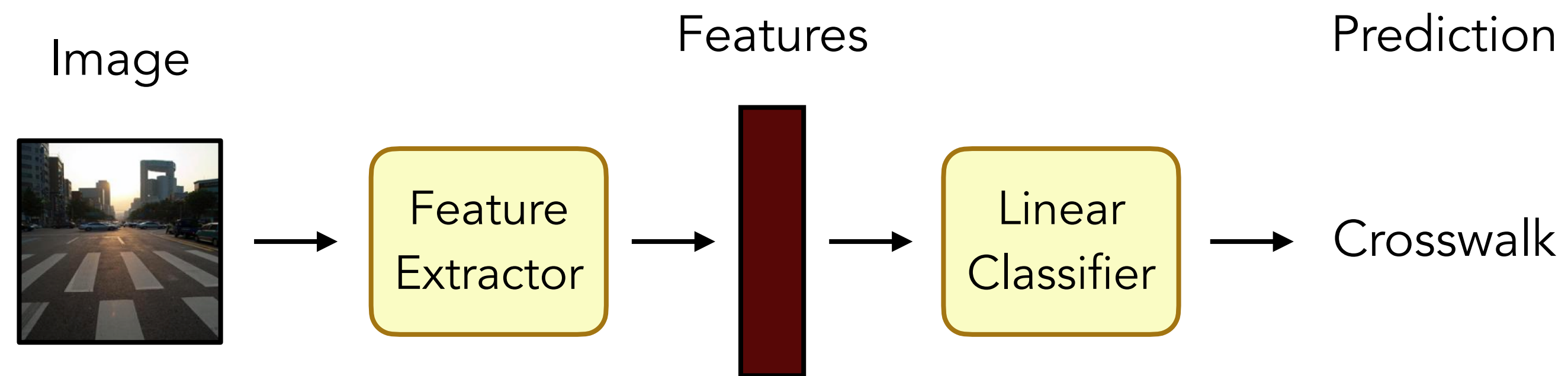
Moritz Böhle



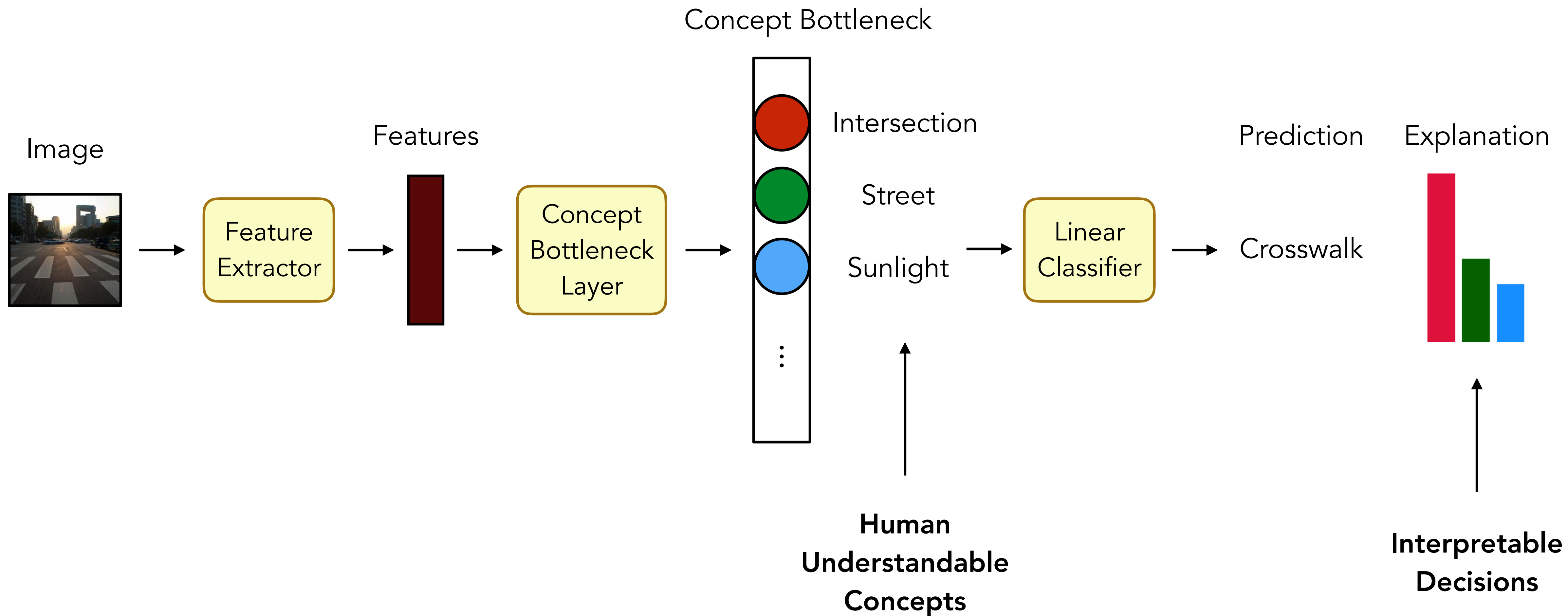
Bernt Schiele

Max Planck Institute for Informatics, Saarland Informatics Campus

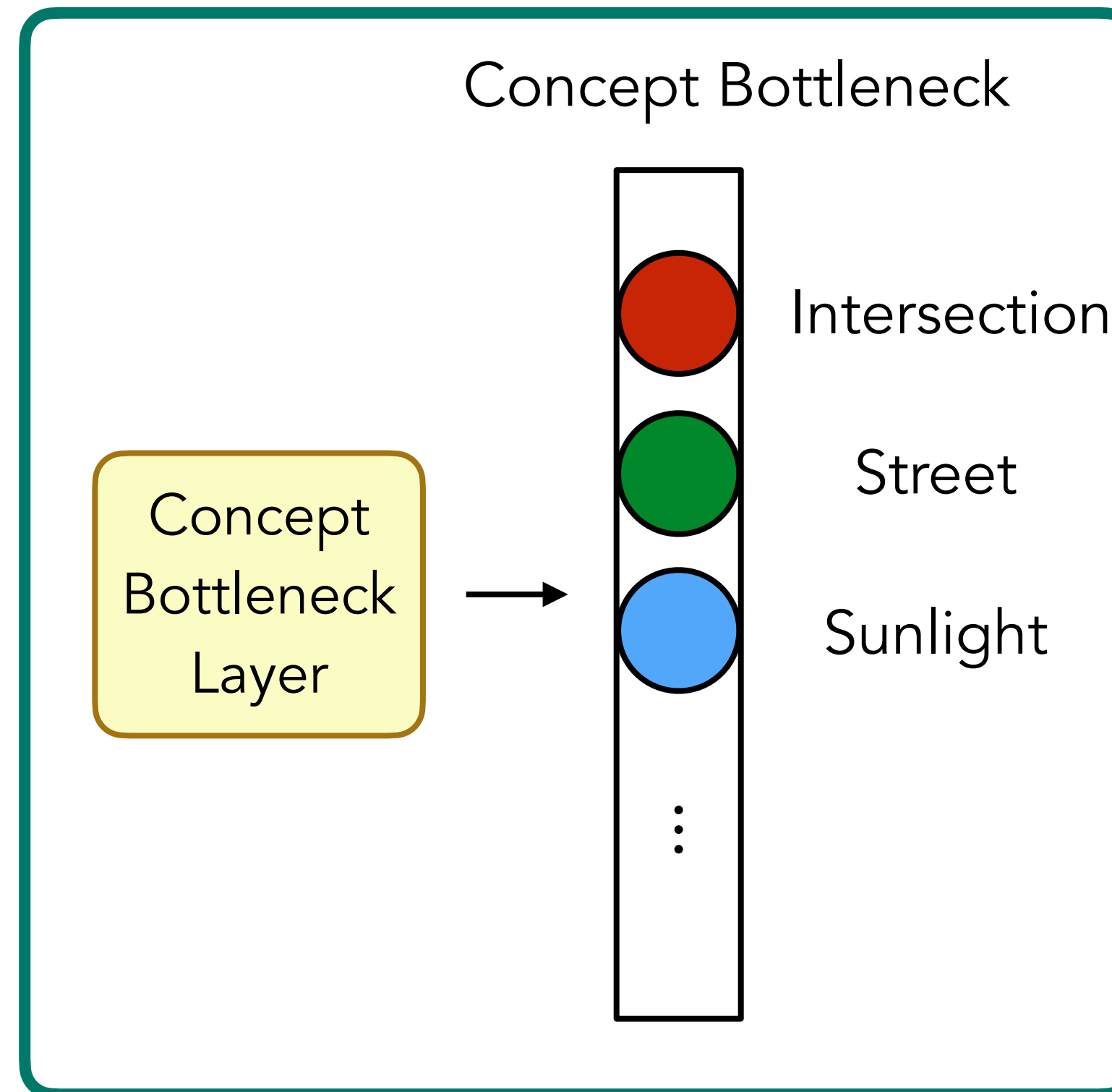
Concept Bottleneck Models



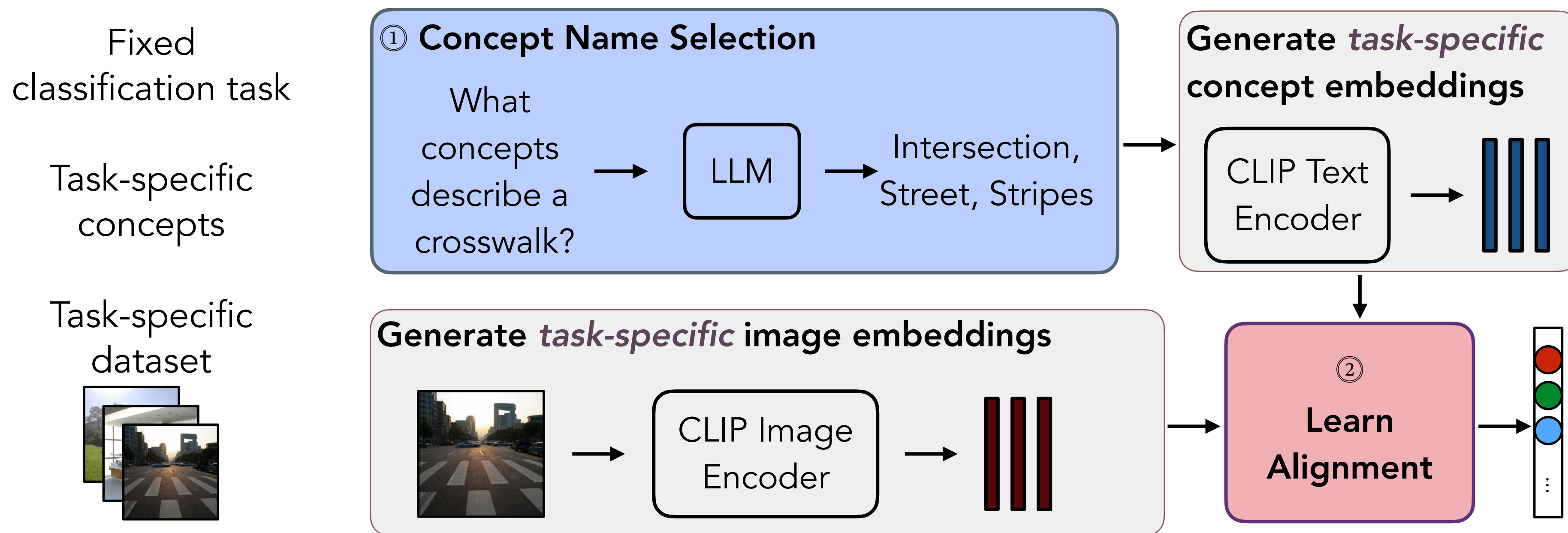
Concept Bottleneck Models



Concept Bottleneck Models



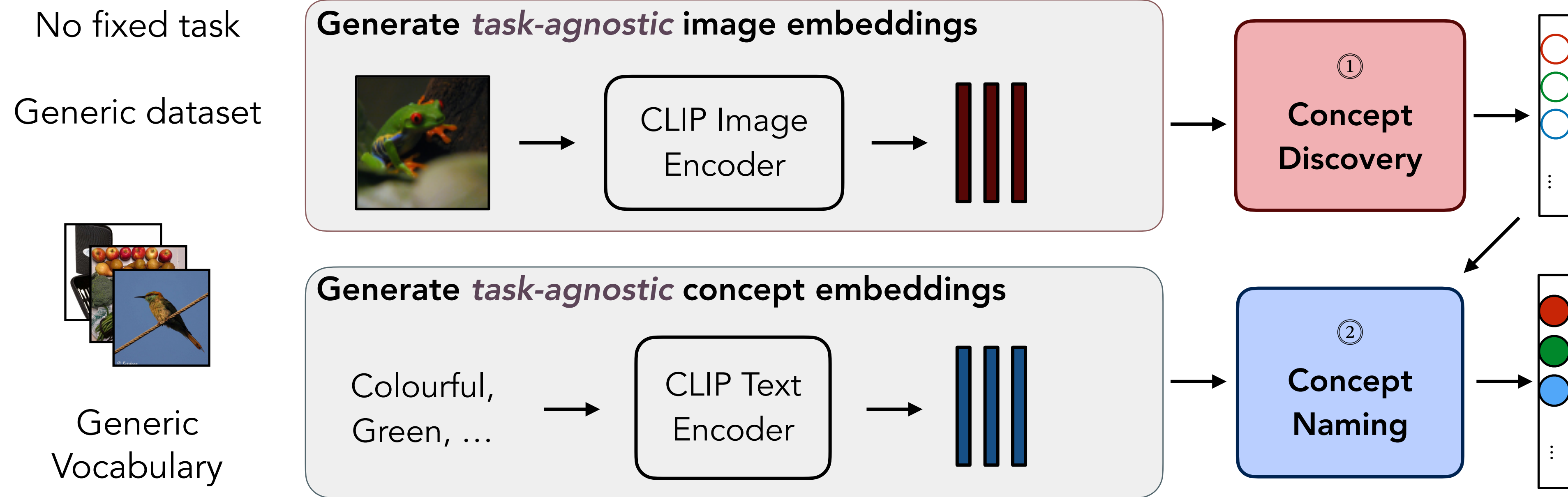
Typical approach¹: Select concepts names, learn mapping



¹Examples: Label-Free CBM [Oikarinen et al., 2023], LaBo [Yang et al., 2023], CDM [Panousis et al., 2023], DCLIP [Menon et al., 2023]

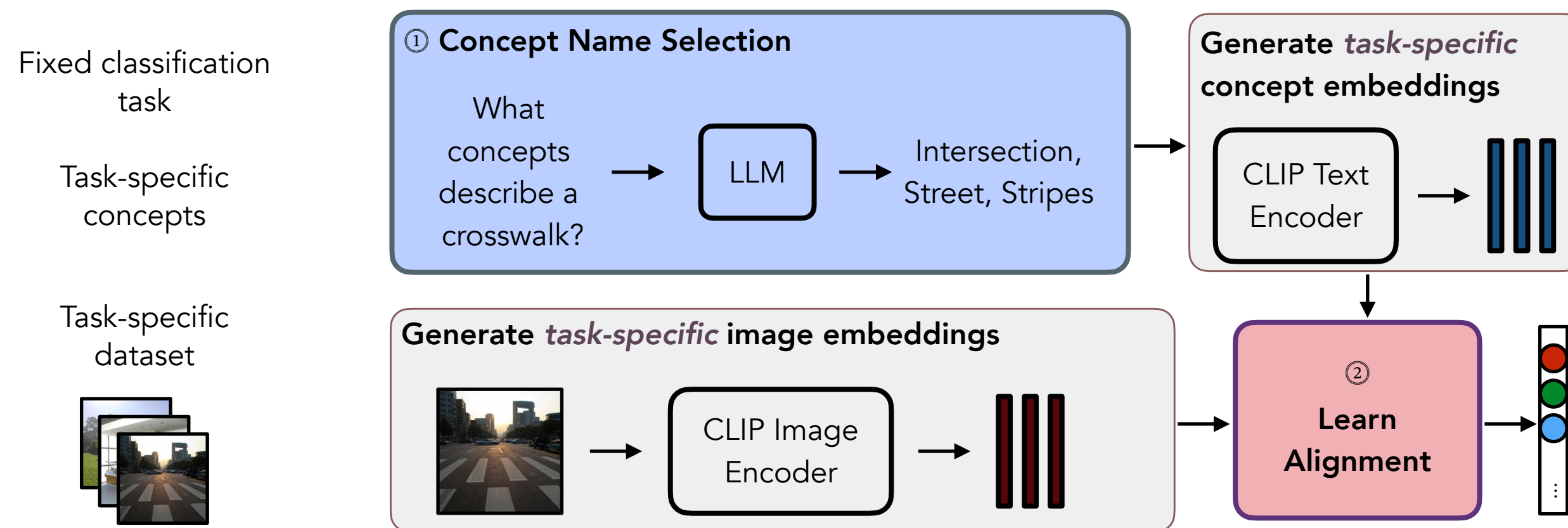


Ours: Discover concepts, then assign names



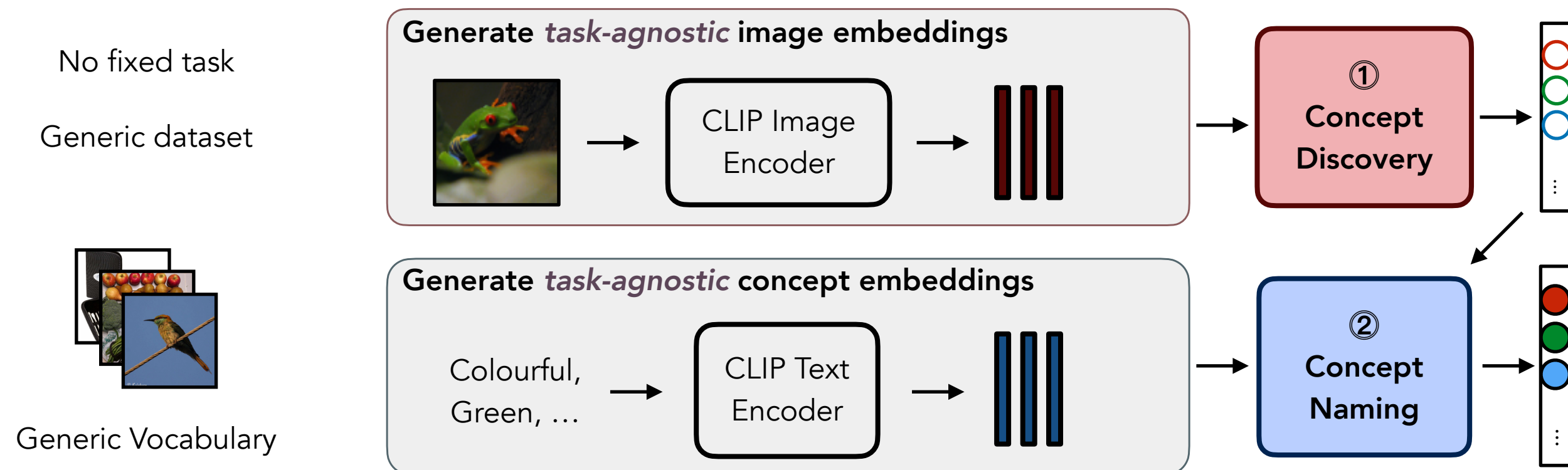
Overview

Typical approach: Select concepts names, learn mapping



- Need to query LLMs for concepts
- Concept bottleneck for single task
- Aligns to predefined concepts

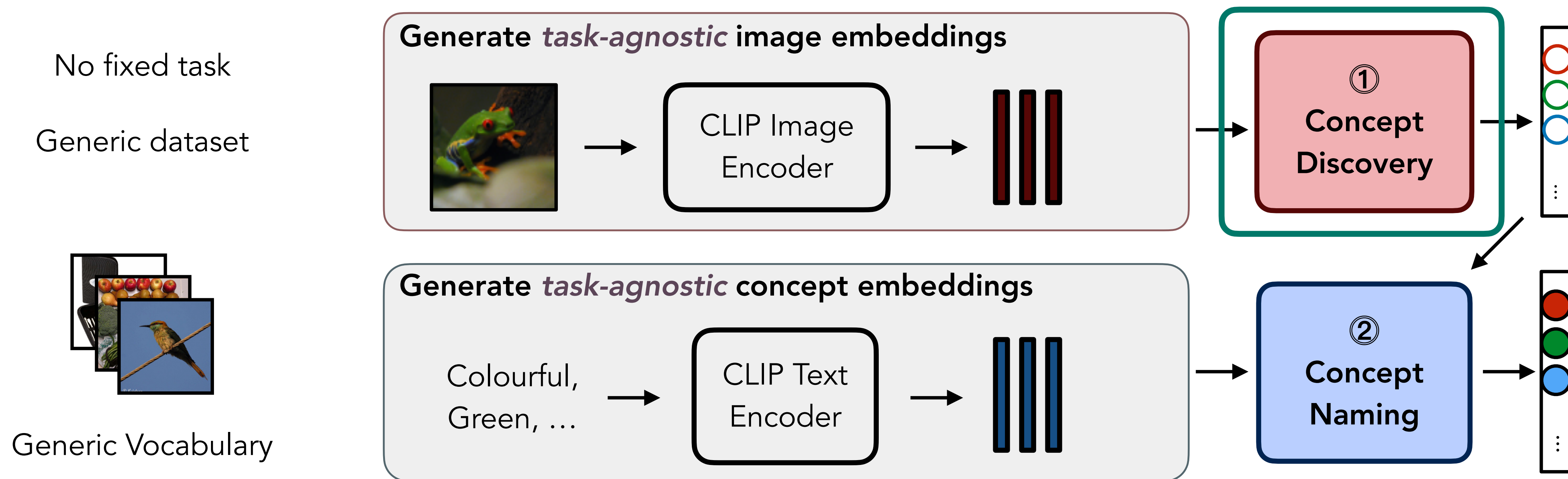
Ours: Discover concepts, then assign names



- No LLM queries needed
- Single concept bottleneck for multiple datasets
- Identifies concepts used by the model

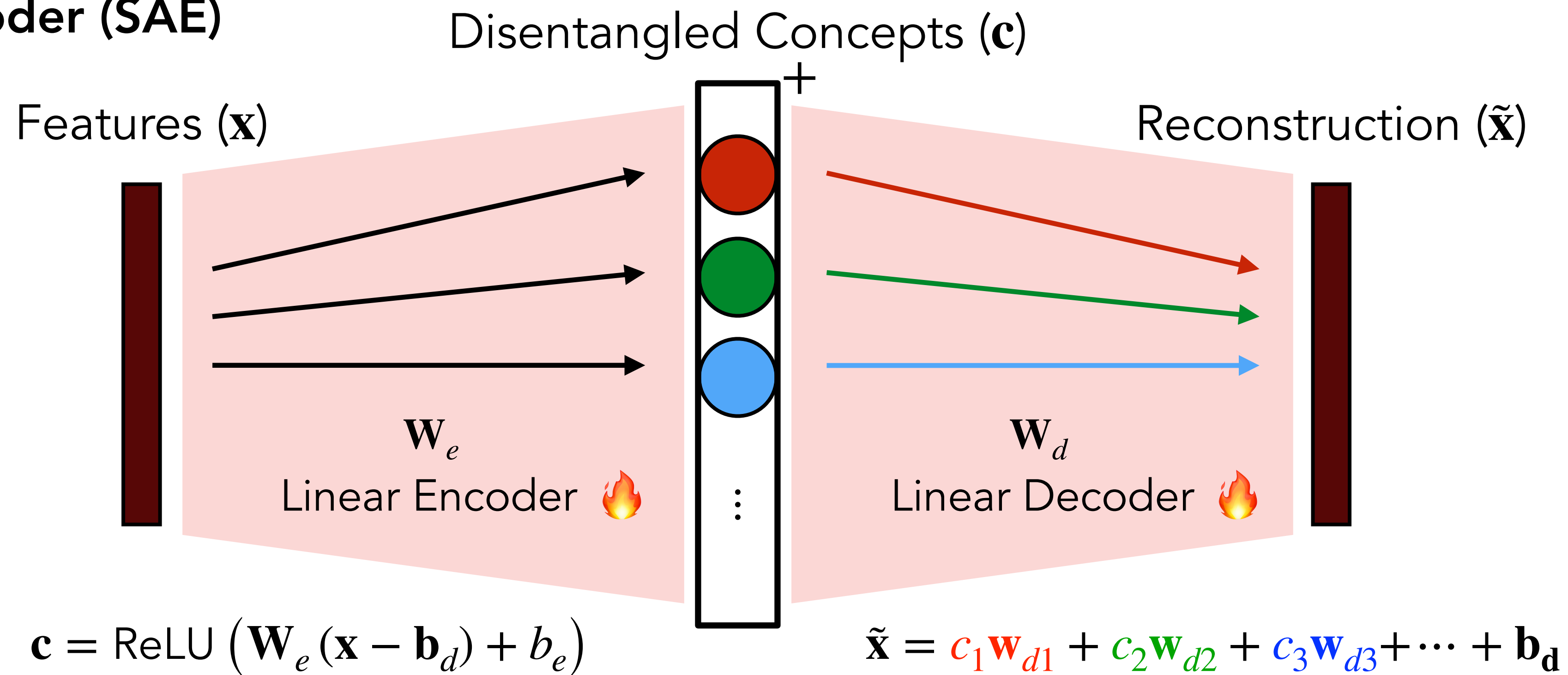


Automated Concept Discovery and Naming



① Concept Discovery

Sparse Autoencoder (SAE)

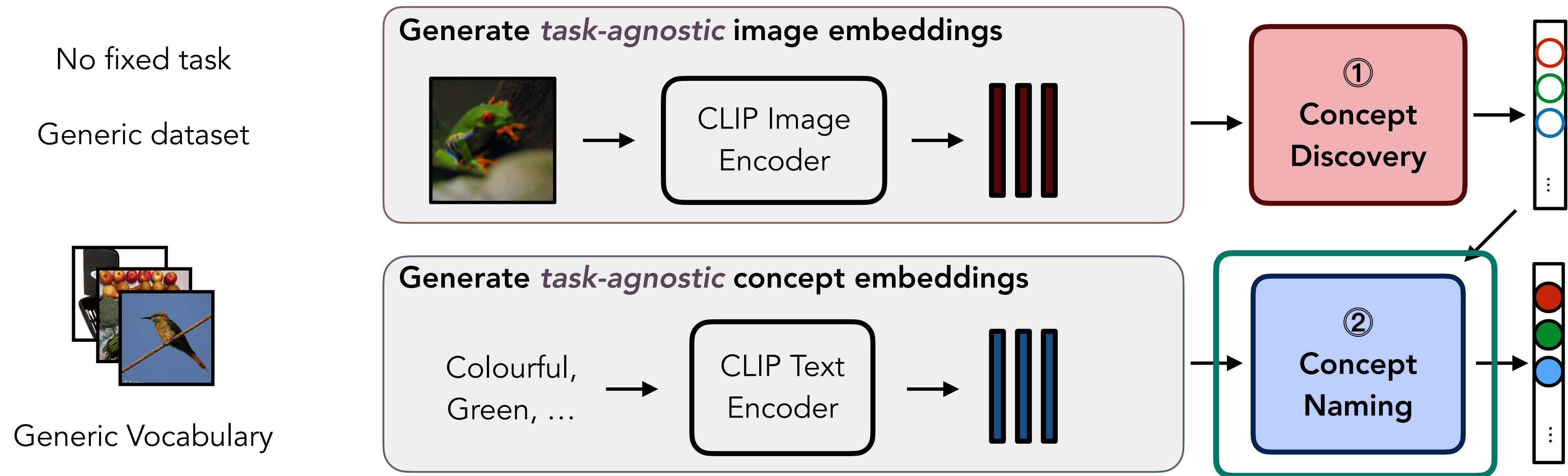


$$\mathcal{L}_{recon} + \lambda \mathcal{L}_{sparse}$$
$$\|\mathbf{x} - \tilde{\mathbf{x}}\|_2^2 \quad \|\mathbf{c}\|_1$$

Sparse Autoencoder: Bricken et al. Towards Monosemanticity: Decomposing Language Models With Dictionary Learning. Transformer Circuits Thread, 2023.

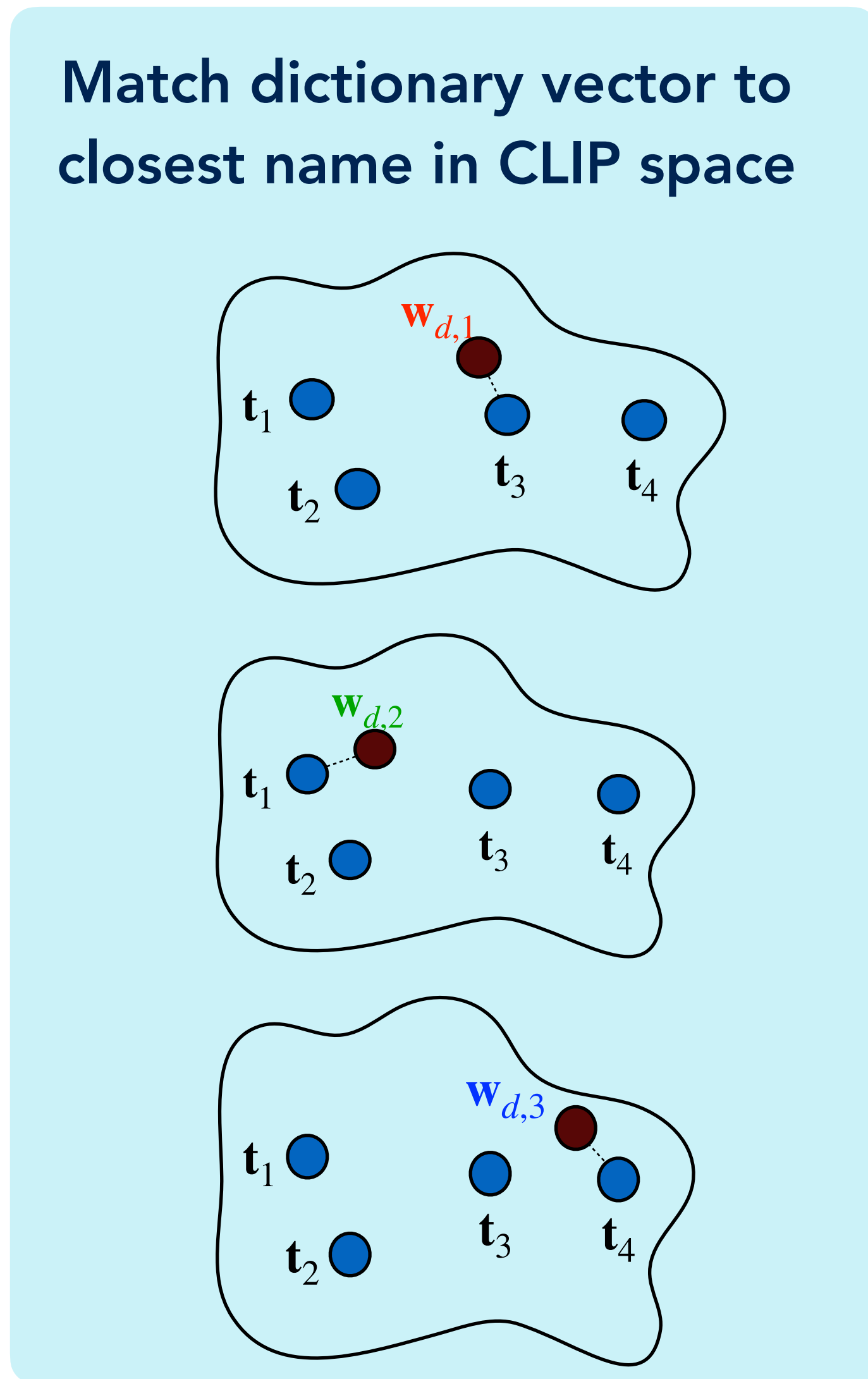
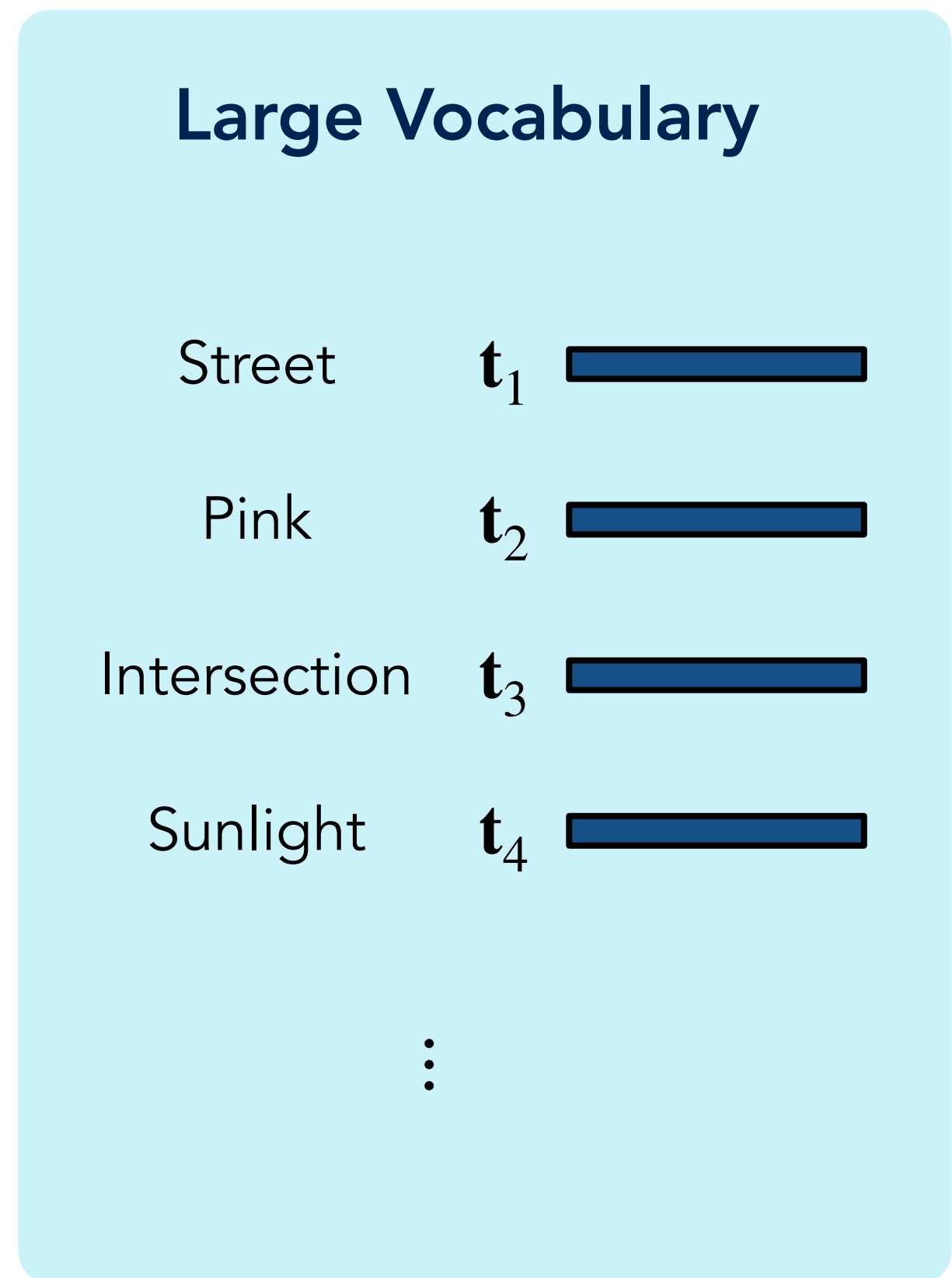


Automated Concept Discovery and Naming



② Concept Naming

$$\tilde{\mathbf{x}} = c_1 \mathbf{w}_{d1} + c_2 \mathbf{w}_{d2} + c_3 \mathbf{w}_{d3} + \dots + \mathbf{b}_d$$



Named Concepts

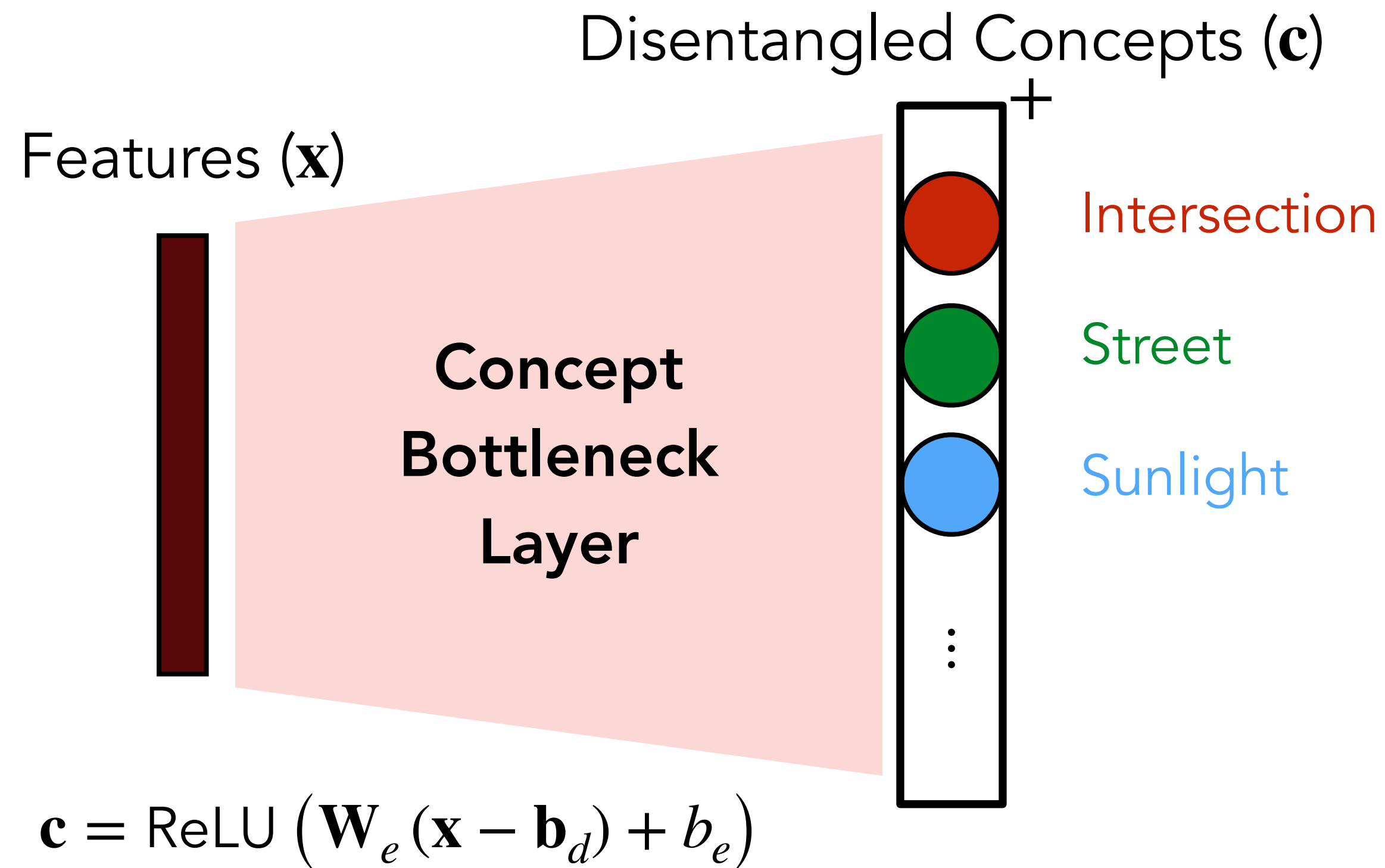
c_1 : Intersection

c_2 : Street

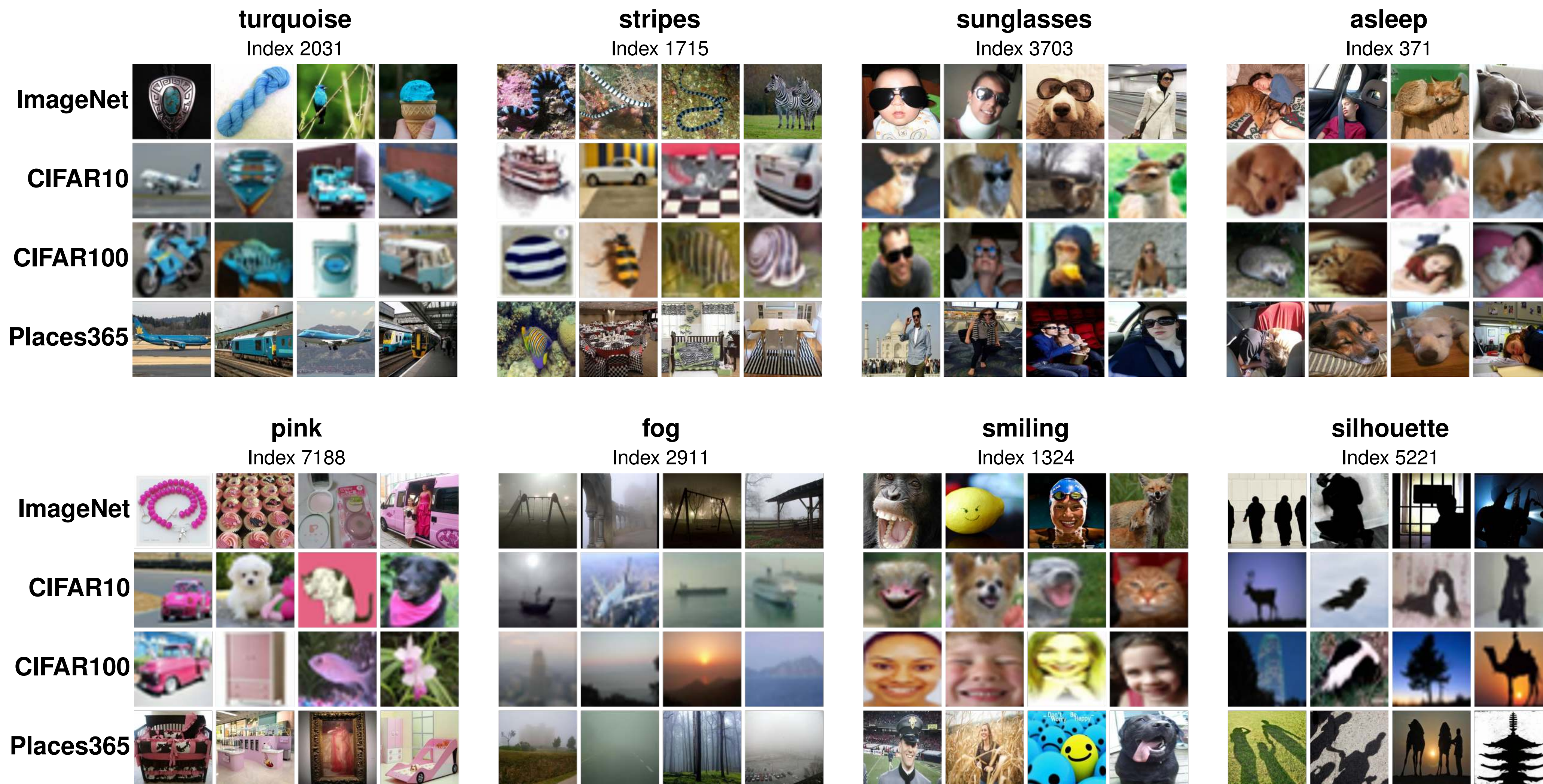
c_3 : Sunlight



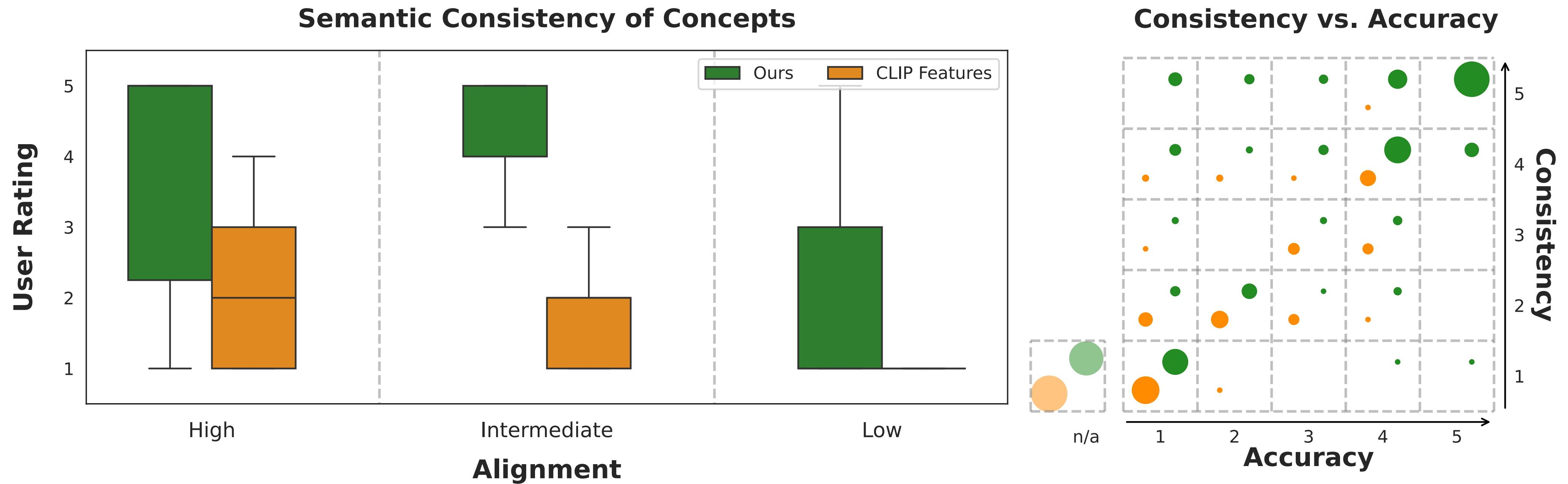
Concept Bottleneck Layer



Consistent and Interpretable Concepts



Consistent and Interpretable Concepts: User Study



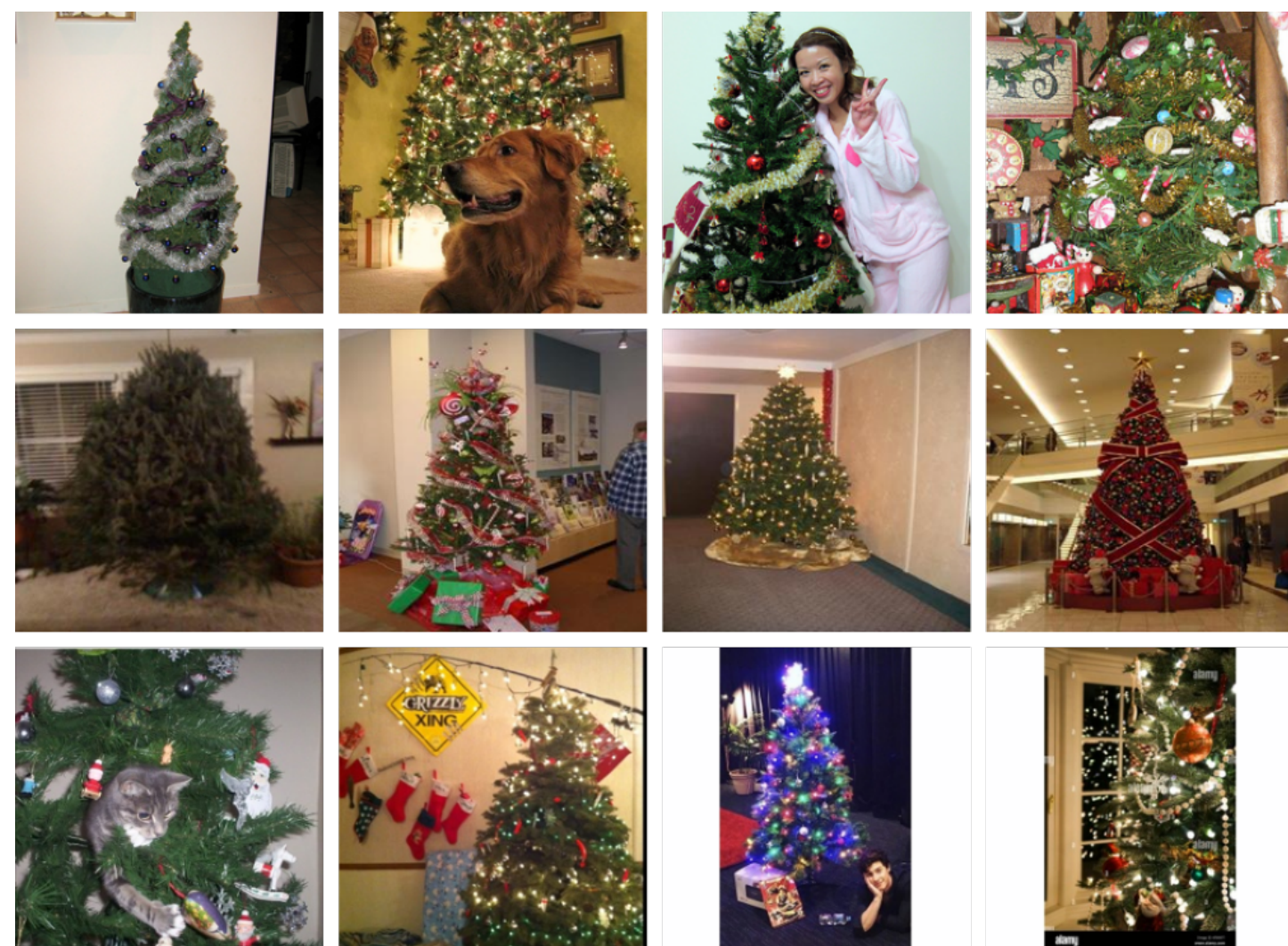
- Better semantic consistency than CLIP features
- High name accuracy for semantically consistent concepts



Granularity Controllable by Vocabulary

tree → **christmas tree**

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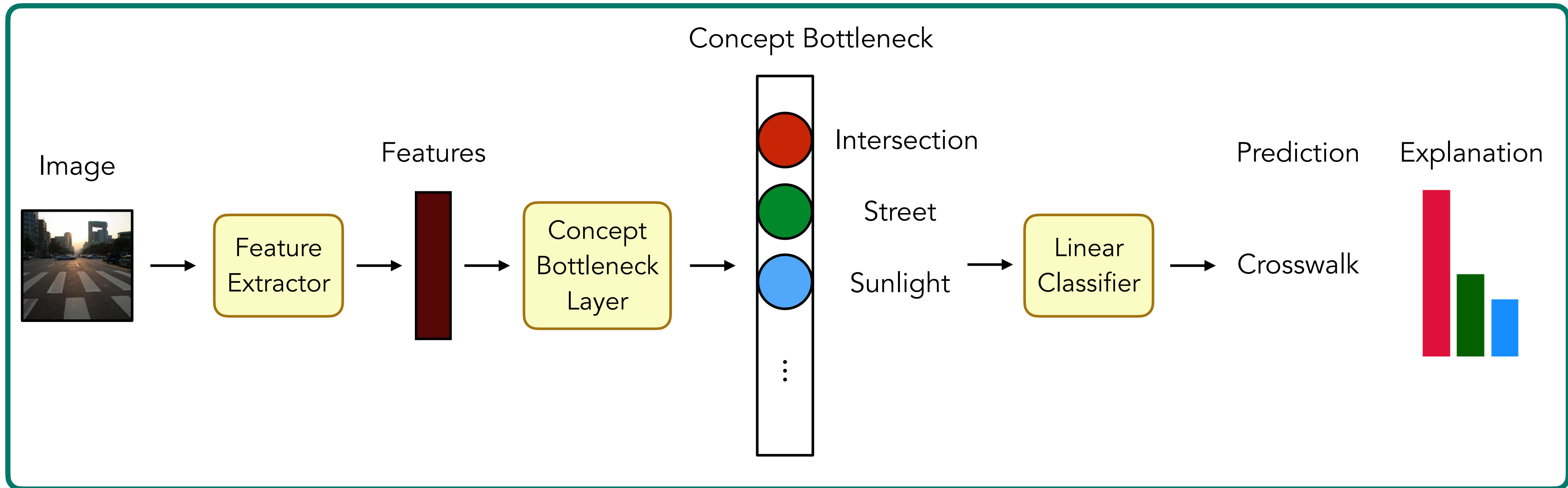


tree → **tree in field**

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Concept Bottleneck Models: DN-CBM



DN-CBM: Results

- Classification Performance

Model	CLIP ResNet-50				CLIP ViT-B/16			
	Places365	ImageNet	CIFAR10	CIFAR100	Places365	ImageNet	CIFAR10	CIFAR100
Linear Probe	53.4	73.3	88.7	70.3	55.1	80.2	96.2	83.1
Zero Shot	38.7	59.6	75.6	41.6	41.2	68.6	91.6	68.7
LF-CBM	49.0	67.5	86.4	65.1	50.6	75.4	94.6	77.4
LaBo	-	68.9	87.9	69.1	-	78.9	95.7	81.2
CDM	52.7	72.2	86.5	67.6	52.6	79.3	95.3	80.5
DCLIP	37.9	59.6	-	-	40.3	68.0	-	-
DN-CBM (Ours)	53.5	72.9	87.6	67.5	55.1	79.5	96.0	82.1

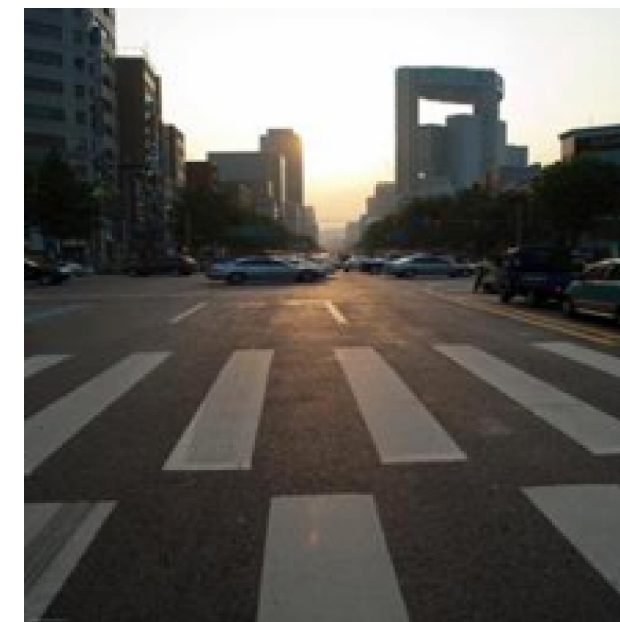
CLIP [Radford et al., 2021], LF-CBM [Oikarinen et al., 2023], LaBo [Yang et al., 2023], CDM [Panousis et al., 2023], DCLIP [Menon et al., 2023].



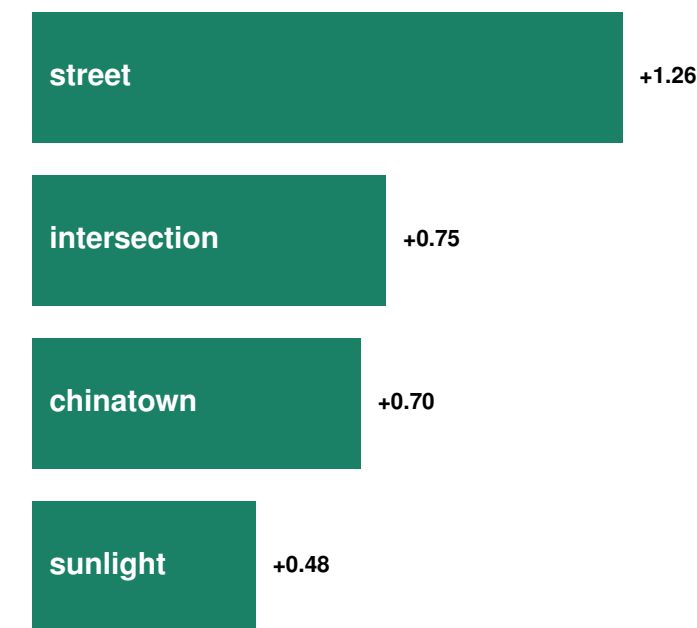
DN-CBM: Results

- Classification Performance
- Explanations for Decisions

Crosswalk



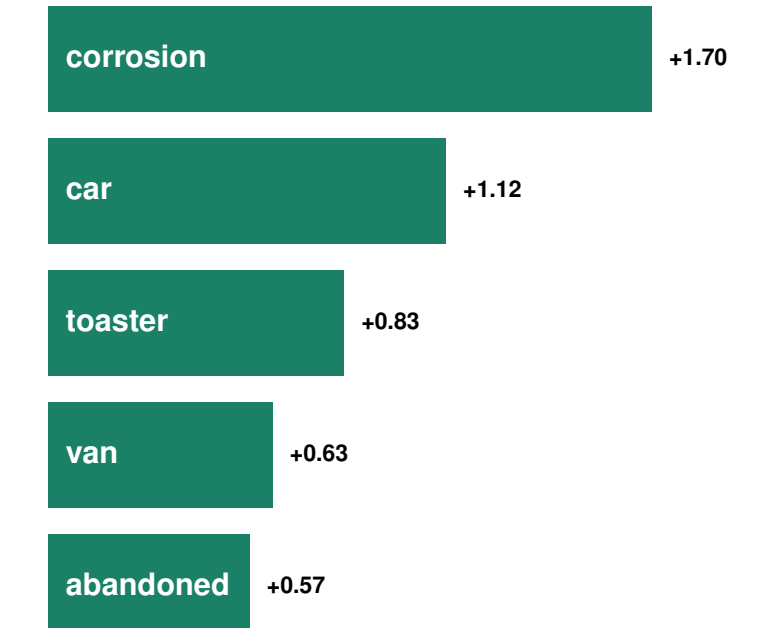
Top concepts



Junkyard



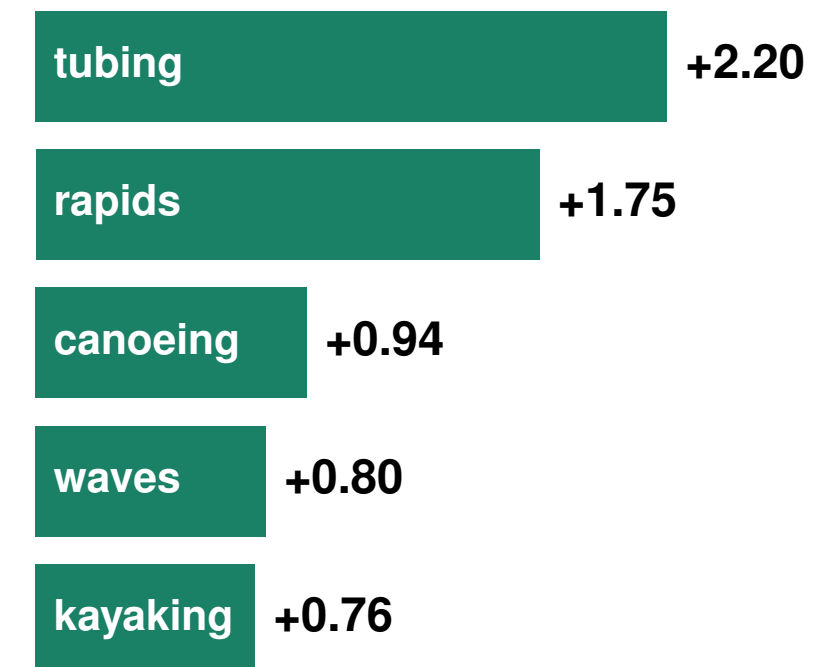
Top concepts



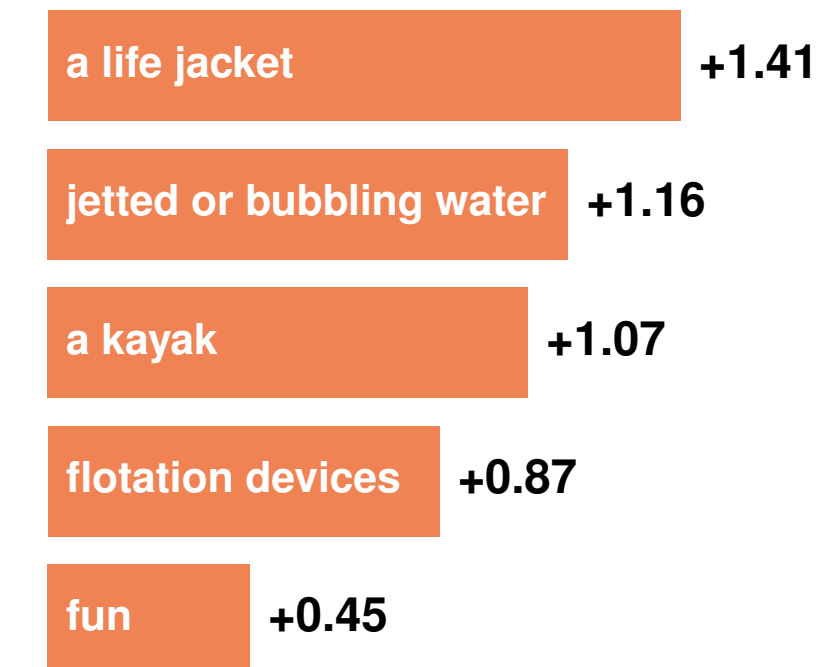
Raft



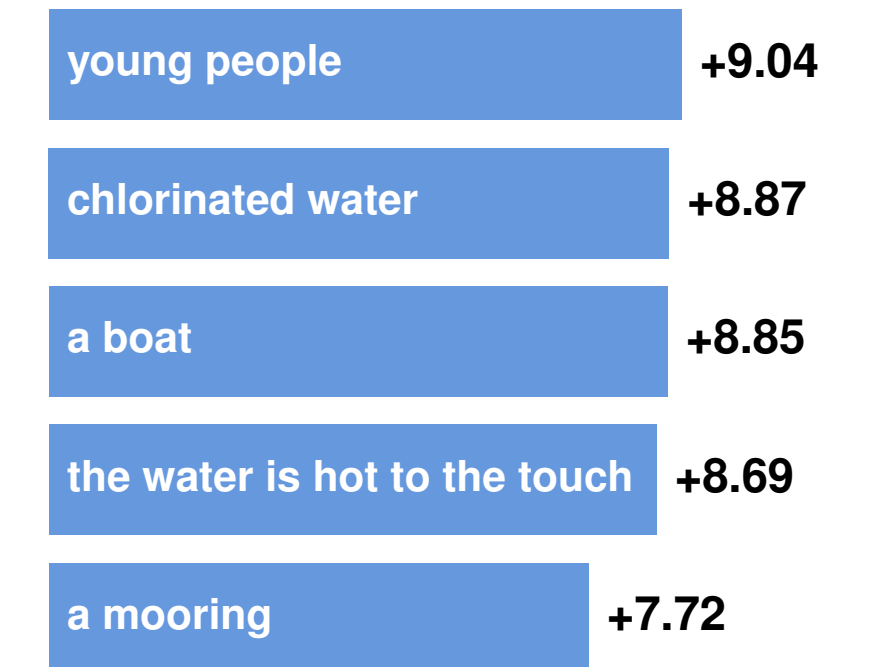
Ours



LF-CBM



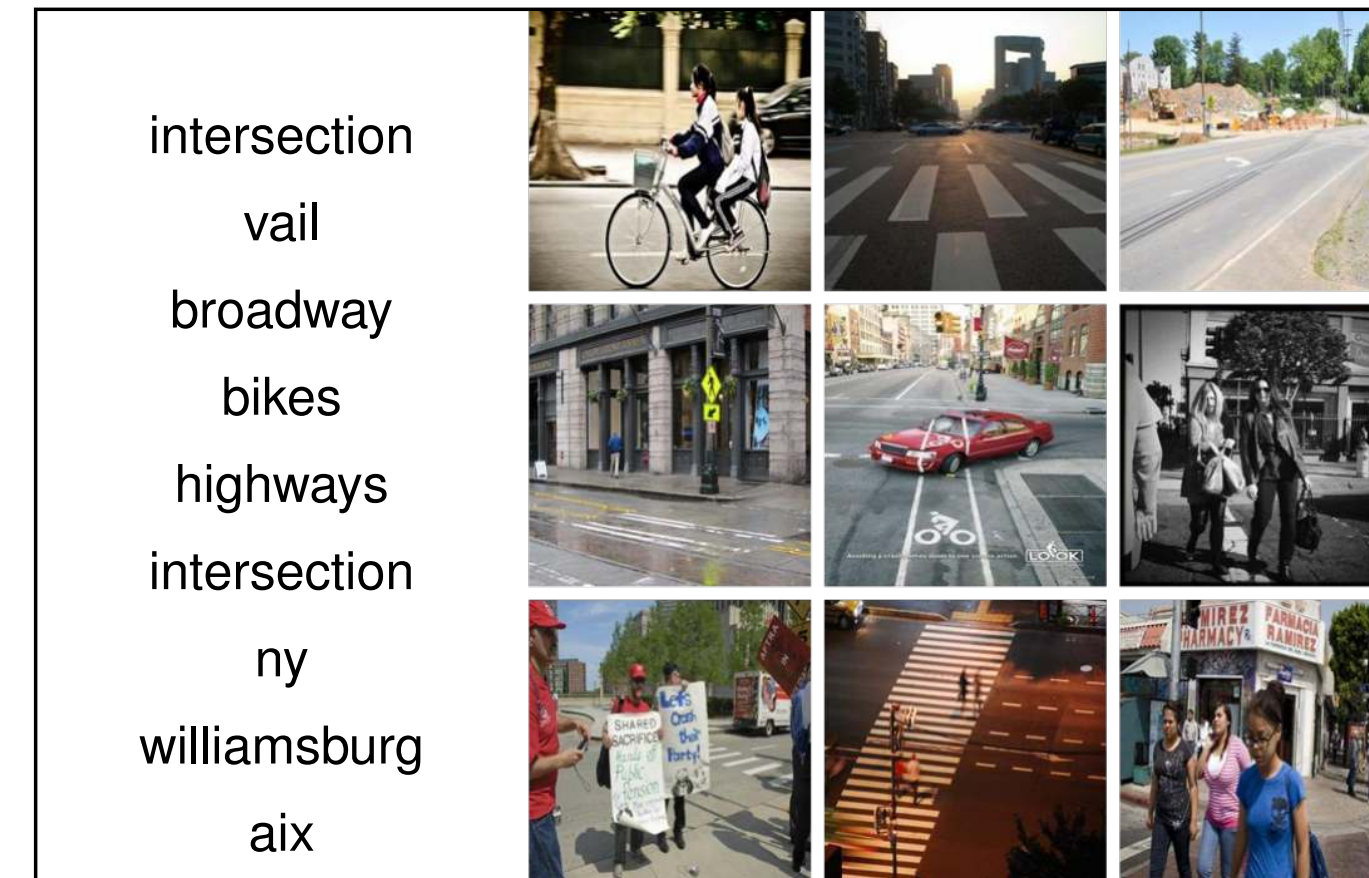
CDM



DN-CBM: Results

- Classification Performance
- Explanations for Decisions
- **Class-level Explanations**

Crosswalk

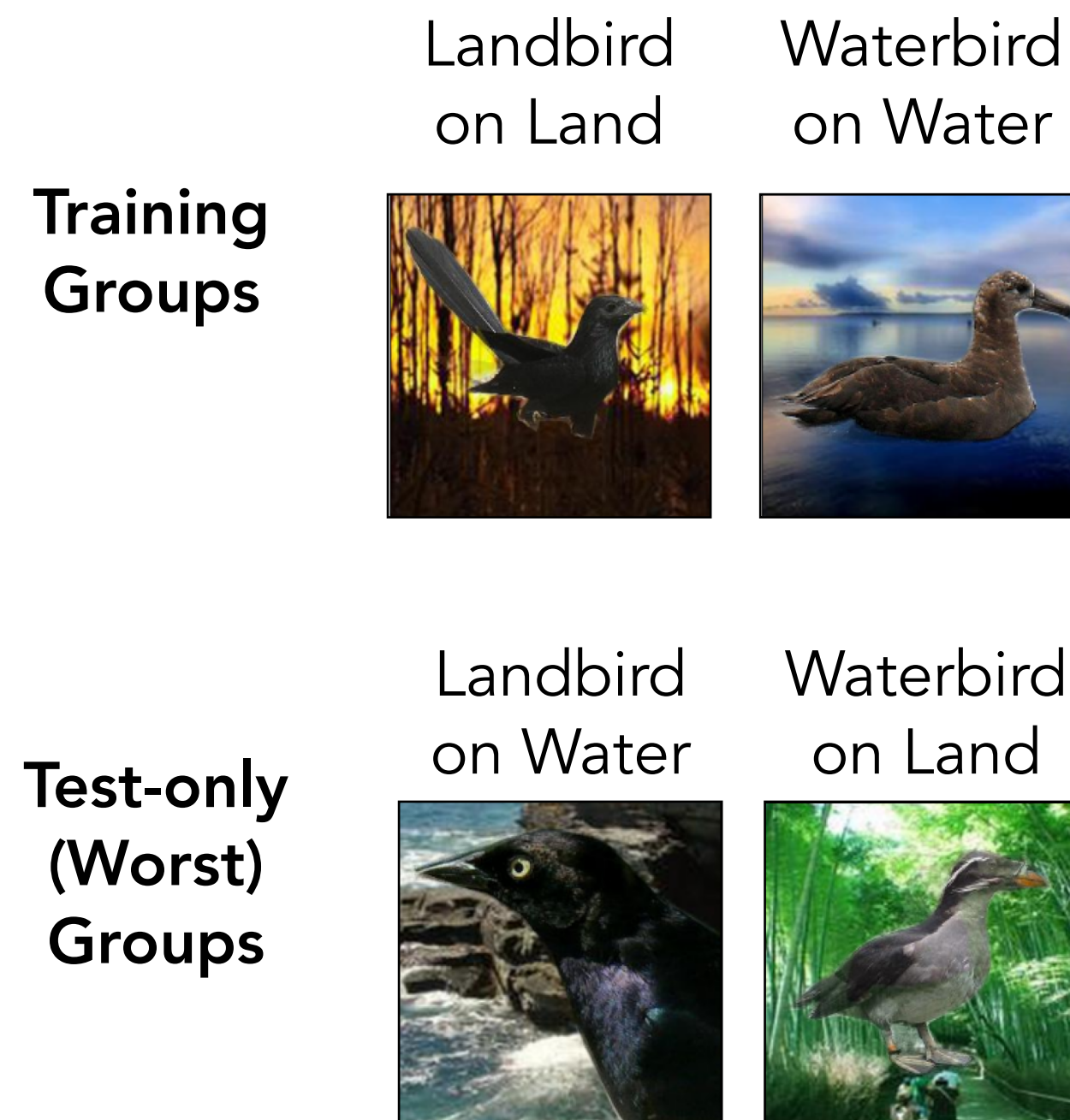


Junkyard



DN-CBM: Results

- Classification Performance
- Explanations for Decisions
- Class-level Explanations
- **Effective Interventions**

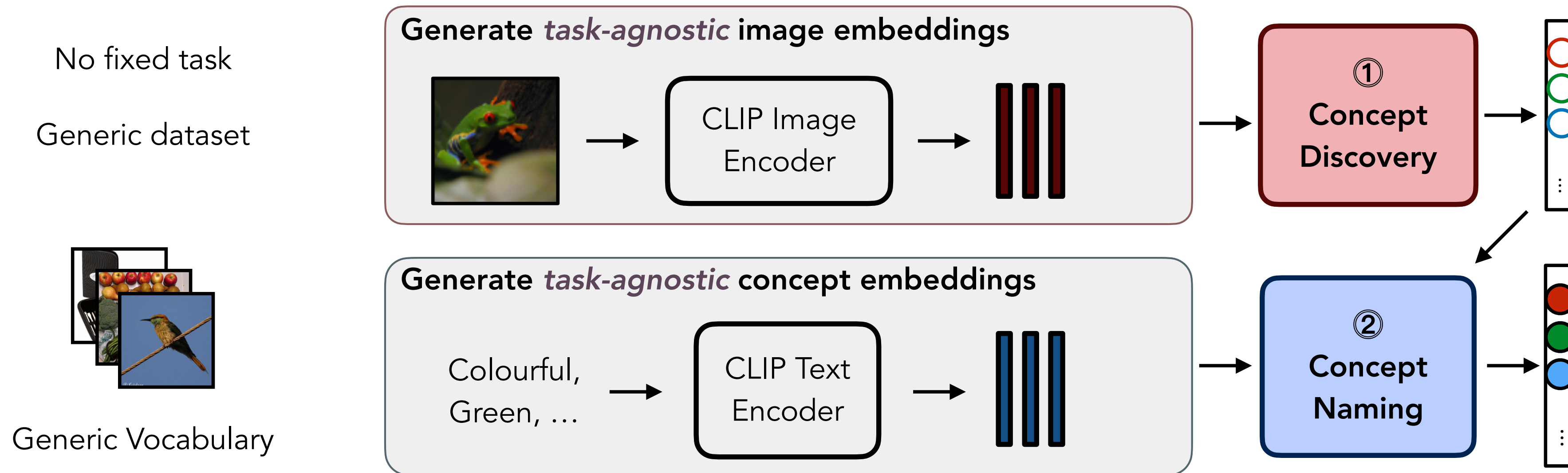
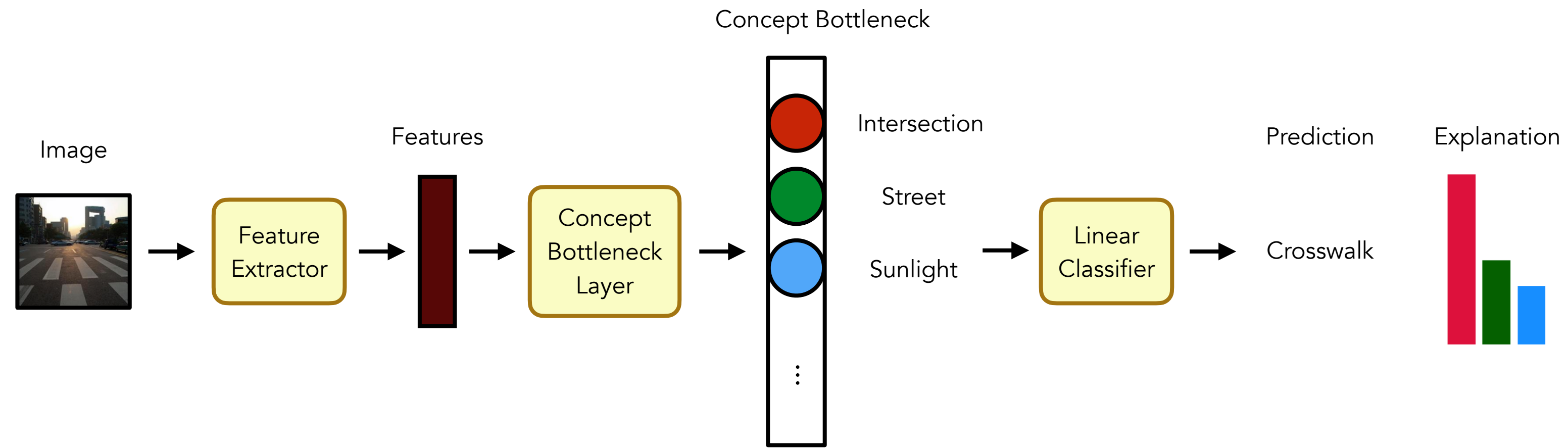


	Bird concepts	Non-bird concepts
Landbird	sparrow, parrot, crow	forest, clic
Waterbird	gull, ducks	landing, beach, canoeing

Model	Overall	Worst Groups	
		Landbird on Water	Waterbird on Land
Before Intervention	82.8	71.3	57.5
Only Bird Concepts	89.4 (+6.6)	86.6 (+15.3)	71.3 (+13.8)
Only Non-bird Concepts	60.8 (-22.0)	28.5 (-42.8)	28.8 (-28.7)



Summary

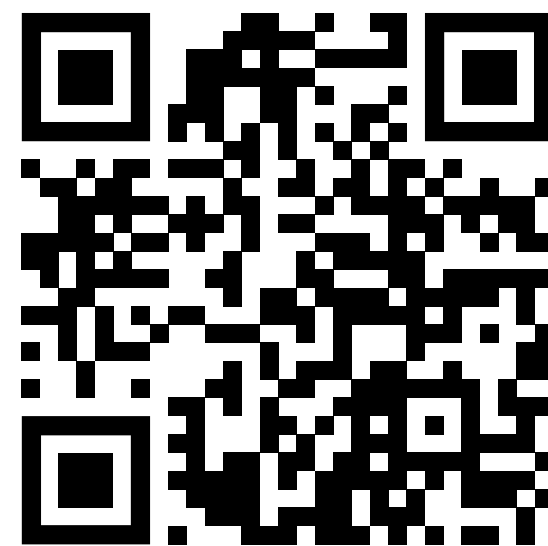


Thank you!

- **Poster Session:** 7
- **Date and Time:** October 4, 2024, 10:30 AM – 12:30 PM

Paper

<https://arxiv.org/abs/2407.14499>



Code

<https://github.com/neuroexplicit-saar/Discover-then-Name>

